CA2-GS4NA

ROBO Cylinder Mini Rod Type Short-Length Single-guide Type Actuator Width 34 mm 24V Servo Motor **Ball Screw Specification/Lead Screw Specification**

■ Model Description

* See page 14 for details on the model descriptions.

RCA2 – GS4NA Series

Encoder type

I: Incremental

specification

* Model number is "I" when used with

simple absolute unit.

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Motor type Lead 20: Servo motor 20W

6: Ball screw 6mm 4: Ball screw 4mm 2: Ball screw 2mm 6S: Lead screw 6mm 4S: Lead screw 4mm 2S: Lead screw 2mm Stroke

30: 30mm A3: ACON-CYB/PLB/POB 50: 50mm A5: ACON-CB/CGB A6: RCON

Compatible controllers N: None

RSEL

Cable length

P: 1 m S: 3 m M: 5 m X□□: Length Designation Option

K2: Connector cable exits from the LA: Power-saving specification

Power-saving specification



(1) The horizontal payload is the value when used in combination with a guide so that a radial load and moment load are not applied to the rod. See P129 for correlation diagrams of the end load and service life when a guide is not installed.

Also note that single-guide types cannot be used if a force is applied in the rotating direction. Use double-guide types in these applications

(2) The payload is the value when the actuator is operated at an acceleration of 0.3 G (0.2G for lead 2, if used vertically and for lead screw specification). The acceleration limit is the value indicated above.

(3) If the actuator is used vertically, pay attention to rod contact because the rod will come down

Actuator Specifications Table

■ Leads and Payloads

Model	Motor output (W)	Feed screw	Lead (mm)	Maximum payload Horizontal (kg) Vertical (kg)		Rated thrust (N)	Positioning repeatability (mm)	Stroke (mm)					
RCA2-GS4NA-I-20-6-①-②-③-④			6	2	0.5	33.8							
RCA2-GS4NA-I-20-4-①-②-③-④	20	20	20	20	20	20	Ball screw	4	3	0.75	50.7	±0.02	30 50
RCA2-GS4NA-I-20-2-①-②-③-④			2	6	1.5	101.5							
RCA2-GS4NA-I-20-6S-①-②-③-④		Lead screw	6	0.25	0.125	19.9							
RCA2-GS4NA-I-20-4S-①-②-③-④	20		4	0.5	0.25	29.8	±0.05	30 50					
RCA2-GS4NA-I-20-2S-①-②-③-④			2	1	0.5	59.7							

■ Stroke and Maximum Speed

Lead	Stroke	30 (mm)	50 (mm)						
W	6	270 <220>	300						
Ball screw	4	200							
Ba	2	10	100						
We	6	220	300						
ead screw	4	20	200						
Le	2	100							

*< > Indicates vertical use

(unit: mm/s)

① Stroke list

Churchen	Standa	rd price				
Stroke (mm)	Feed	screw				
(111111)	Ball screw	Lead screw				
30	_	_				
50	_	_				

Legend ① Stroke ② Compatible Controllers ③ Cable length ④ Option

4 Options

Title	Option code	See page	Standard price
Connector cable exits from the front	К2	_	_
Power-saving specification	LA	_	_

③Cable Length

Type	Cable symbol	Standard price
Standard type (Robot cable)	P (1m)	_
	S (3m)	_
	M (5m)	_
	X06 (6m) ~ X10 (10m)	_
Special length	X11 (11m) ~ X15 (15m)	_
	X16 (16m) ~ X20 (20m)	_

^{*} The standard cable for the RCA2 is the robot cable.

Actuato	r Specifications							
	Item	Description						
Drive System		Ball screw/Lead screw, ø6mm, rolled C10						
Lost motion		Ball screw: 0.1mm or less Lead screw: 0.3 mm or less						
Frame		Material: Aluminum, white alumite treated						
Ambient operating temperature, humidity		0 to 40°C, 85% RH or less (Non-condensing)						
Service life	Lead screw specification	Horizontal specification: 10 million cycles, Vertical specification: 5 million cycles						

Dimensional Drawings

www.intelligentactuator.com

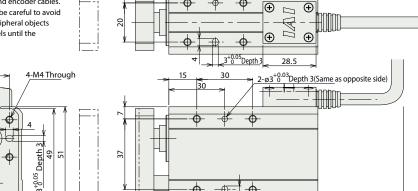


ø<u>3^{+0.03}Dept</u>h

- *1 Connect the motor and encoder cables.
- *2 During home return, be careful to avoid interference from peripheral objects because the rod travels until the mechanical end.

30

34



2-3^{+0.05}Depth 3 (Same as opposite side)

ME *2

10

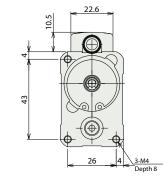
ø3^{+8.03}Depth 3

4-M4 Depth 5

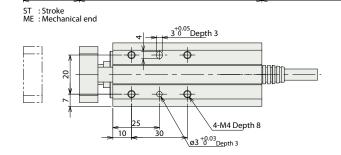
8-M4 Depth 5 (Same as opposite side

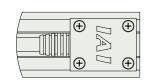
Secure at least 100mm

(300)



Cable joint connector *1





Changing the cable connector outlet direction Model: K2 (Exits from the front)

* Rotate 180° relative to the standard specification.

■ Dimensions and Weight by Stroke

Stroke	30	50
L1	98	118
L2	80	100
Mass (kg)	0.55	0.63

Applicable Controllers

The actuators on this page can be operated by the controllers indicated below. Please select the type depending on your intended use.

	F. A	Man annahan af	Power	Control method							D-f									
Name	External view	Max. number of connectable axes	supply	Positioner	Pulse-					Network option *1									Maximum number of positioning points	Reference page
	VICVV	COTHICCIADIC AXCS	voltage	train Program	Program	DV	CC	CIE	PR	CN	ML	ML3	EC	EP	PRT	SSN	ECM	positioning points	page	
ACON-CB/CGB	No.	1		● * Option	* Option	-	•	•	•	•	•	•	•	•	•	•	-	-	512 (768 for network spec.)	
ACON-CYB/PLB/POB		1	24VDC	* Option	* Option	-	-	-	-	-	-	-	-	-	-	-	-	-	64	Please contact
RCON	HEM IL	16 (ML3,SSN, ECM are 8)		-	-	-	•	•	•	•	-	-	•	•	•	•	•	•	128 (No position data for ML3, SSN, ECM),	IAI for more information.
RSEL	THE TO	8		-	-	•	•	•	•	•	-	-	-	•	•	•	-	-	36000	

^{*1} For network abbreviations such as DV and CC, please contact IAI.

More controller info is available in the General Controller Catalog PDF.

